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## Initial Development of a Pulsed **Electrothermal Thruster**

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#### I. Introduction

HE pulsed electrothermal (PET) thruster<sup>1-4</sup> generates stagnation pressures of tens to hundreds of atmospheres by operating in a pulsed mode. For pulse widths of 10  $\mu$ s, the electrode and insulator surfaces stay below their melting points. The high operating pressure increases recombination in the nozzle to reduce frozen flow losses and exhaust gas temperatures.

The PET thruster system includes the thruster head, propellant injection system, capacitive energy storage system, power supply, and control system. The thruster head contains a cylindrical capillary discharge chamber with end electrodes, with water propellant injected along the centerline. The discharge heats the injected water to a high temperature and pressure during the pulse, creating a thrust impulse. The pulsed discharge breaks down at several hundred pulses/s to create average thrust. The 5-mm-inner-diam (ID) × 56-mmlong cylindrical capillary insulator is made of prestressed silicon nitride or alumina4; smaller boron nitride insulators with 4- and 3.2-mm ID were also used.

The PET thruster head is water cooled, enabling thermal heat loss to be measured calorimetrically. The thruster is not sensitive to electrode polarity and is operated here with the propellant injected through the anode at the stagnation end. The grounded cathode is located at the sonic throat. The anode material is 0.15% alumina dispersion-strengthened copper or sintered tungsten alloy. The 400:1 contoured exhaust nozzle contains the tungsten alloy cathode as an insert.

Water propellant is continuously injected through a straight 75-100  $\mu$ m orifice with an L/D (length/diameter) of 1.5-5.0. At 200-400 pulses/s, the propellant only travels a few centimeters between pulses, so that injected, unevaporated liquid is

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heated by two or three pulses. The water is injected either as a straight jet or atomized spray. A finite element thermal model is used to predict and avoid the onset of boiling at the orifice. A ceramic Macor thermal insulator prevents propellant boiling when operating near the ideal propellant flow. The water flow requirement for the PET thruster at 1500-s specific impulse is 6 mg/s/kW, giving 60 μg/pulse at a typical pulse rate of 100 pulses/s/kW.

Spray injection is achieved through the technique of aerated liquid atomization.<sup>5</sup> Helium gas is introduced upstream of the orifice, with the liquid and gas passing through the orifice as a mixture, producing a fine 20  $\mu$ m spray with a total spray angle of 15-20 deg. This approach uses a gas mass flow rate of 1-10% of the liquid mass flow rate. The resulting aerated liquid spray intersects the hot wall of the capillary where the droplets are partially evaporated, forming a vapor film that prevents further wall contact.

Based on studies of droplets exposed to gas dynamic shock waves, 6 it is probable that axial vapor flow causes the drops to shatter on a time scale of a few  $\mu$ s. The Weber number  $\rho u^2 d/\sigma$ for 20  $\mu$ m drops is  $We = 2 \times 10^3$  near the throat, greatly exceeding the critical Weber number  $We \approx 5$ . This shattering process is crucial to the coupling between the water and the discharge.7

The thruster is driven at 200-400 pulses/s by a 10 section, 10  $\mu$ F, 0.48  $\Omega$  pulse-forming network (PFN), using phenyl xylyl ethane (PXE) dielectric capacitors with an estimated dielectric loss of 0.2 W at 5 kW. Predicted life is 109-1011 pulses. Demonstrated life here is  $> 2 \times 10^7$  pulses with zero failures and 10<sup>11</sup> pulses in a similar application, so that capacitor life is no longer considered an issue for the PET thruster. The PFN is designed to match the electrical resistance of the discharge and to prevent electrode or insulator surface melting during the pulse.<sup>4</sup> The thruster is tested with axis vertical on a 1 m<sup>3</sup> vacuum tank, with a tank pressure of 1 Torr.

### II. Operational Tests

Tests were run at the several-kilowatt level to measure thruster operating parameters. Test experience with 56-mmlong ceramic insulators is summarized in Table 1, covering  $26.6 \times 10^6$  total pulses.<sup>4</sup>

Insulator ablation was measured with dimensional gauge pins after each test. In no case was any erosion observed with Si<sub>3</sub>N<sub>4</sub>, Al<sub>2</sub>O<sub>3</sub>, or BN. Although the insulators experienced sputtering from the eroding electrodes, no dimensional change was detected and no change in electrical behavior was observed.

Electrode erosion was measured for thruster average power of 1.3-3.6 kW. Electrode mass loss for the PET thruster is plotted vs average thruster power in Fig. 1, covering a variety of anode geometries, anode materials, and arc conditions. Because plasma heat transfer does not cause electrode surface melting, the observed erosion is probably due to coulombic charge transfer. Experimental measurements for vacuum arcs show<sup>8,9</sup> that charge transfer erosion decreases with pressure to  $2-3 \mu g/C$  at 500 Torr. Most of the present data fall below 10  $\mu$ g/C, much of it in the 2-4  $\mu$ g/C range, with cathode erosion

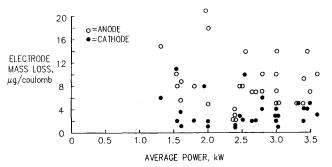


Fig. 1 Electrode mass loss, showing lower erosion for the cathode.

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Table 1 Ceramic insulator tests

Insulator type	Si <sub>3</sub> N <sub>4</sub>	Al <sub>2</sub> O <sub>3</sub>	BN	BN	BN
Inner diameter, mm	5.0	5.0	5.0	4.0	3.2
Total tests	37	16	1	1	2
Pulses $\times 10^{-6}$	18.7	5.5	0.07	1.1	1.2

Table 2 Erosion at high propellant utilization,  $\eta_{pu}$ 

	Test number					
	64	65	66	67		
Total pulses $\times 10^{-6}$	0.7	1.0	2.0	1.1		
Average power, kW	2.5	3.3	3.0	3.0		
$\eta_{pu}$	0.67	0.66	0.95	0.91		
Helium mass flow fraction	0.0	0.0	0.05	0.05		
Si <sub>3</sub> N <sub>4</sub> erosion, μg/C	8.0	4.5	10.2	5.3		
Cathode erosion, µg/C	3.4	4.5	2.4	1.2		
Arc voltage, kV	1.2	1.5	1.5	1.5		

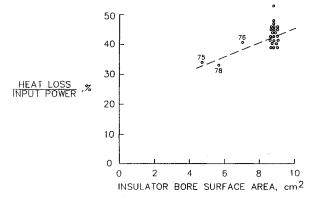


Fig. 2 Heat loss as a function of insulator surface area, determined calorimetrically.

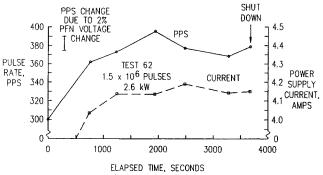


Fig. 3 Variation in pulse rate and current for a 1-h test.

considerably less than anode erosion. The lifetime of the electrodes can be extrapolated using the erosion data, resulting in  $3 \times 10^7$  pulses per gram of electrode.

The ratio of ideal mass flow rate to the actual mass flow rate is called the propellant utilization efficiency  $\eta_{pu}$ . The ideal mass flow rate is calculated from the water enthalpy h at 100% of the actual pulse energy, based on discharge conditions:  $\Delta m_{\rm ideal}$  (kg/pulse) =  $E_{\rm pulse}/h$ . Propellant utilization < 1.0 reduces specific impulse, and so  $\eta_{pu}$  must be kept as high as possible. Erosion tests at high propellant utilization are summarized in Table 2.

Table 2 shows that injection with and without a 5% helium flow fraction has little effect on erosion or thruster voltage. All tests in Table 2 were performed without boiling the propellant or without an adverse effect on erosion.

The water cooling jacket on the PET thruster permits calorimetric measurement of the thermal efficiency. Data for the time-averaged cooling power on 28 tests are summarized in Fig. 2, which plots the thermal loss fraction as a function of bore surface area. Most of the data from Fig. 2 (open circles) are for a 5-mm-diam × 56-mm-long ceramic insulator. Three data points (tests 75-78) show higher thermal efficiency associated with reduced surface area capillaries. The thruster thermal efficiency for tests 75 and 78 is about 0.66.

Performance degradation is measured in terms of the arc electrical properties. The variations in pulse rate and power supply current during a run of  $1.5 \times 10^6$  pulses are shown in Fig. 3, where the error bar shows the expected range in pulse rate from a 2% variation in PFN voltage. Pulse rate variation is also a sensitive indicator of anode sputtering because a conductive coating on the insulator would reduce PFN voltage and raise pulse rate, which was not observed. Over this test period, degradation was probably < 1%.

#### III. Analysis and Conclusions

For pulses that generate quasisteady conditions in the capillary, the nozzle enthalpy flux  $\dot{m}h$  is equal to the plasma radiation intercepted by the propellant, thus giving:  $\eta_{\rm therm} = (Q_{\rm rad})_{\rm prop}/(I^2R)$ . This expression emphasizes that are radiation must be absorbed by the propellant, achieved either by coating the wall with an absorbing water layer or by spray injection of micron-size drops. For the latter case, the thermal efficiency is derived from the ratio of the wall surface area  $\pi DL$  to the droplet surface area  $A_{\rm drop}$ . For the present 5-kW thruster at 250 pulses/s,  $\eta_{\rm therm} = 0.90$  for 0.1  $\mu$ m drops.

Mechanisms for droplet shattering have been verified by us with high-speed photomicrographs? showing shattering on a time scale of 15-30  $\mu$ s after discharge initiation. The Weber number criterion predicts drop diameters of < 0.1  $\mu$ m near the nozzle exit. We also know that reducing capillary diameter raises the thermal efficiency, as shown in Fig. 2. This is consistent with the expected increase in pressure and flow velocity in the capillary, which in turn accelerates the process of drop breakup, evaporation, and radiation absorption.

Observed thruster erosion is consistent with erosion experience from vacuum arc discharges. The thruster is dependent on breakup of the injected liquid propellant for efficient operation, and so may benefit from longer discharge pulses than the  $10 \mu s$  used here. Thruster erosion can also be reduced with higher voltage operation to reduce coulomb transfer.

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